

Solving decomposable sparse polynomial systems

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Introduction

We'd like to solve polynomial systems more efficiently.

- Every polynomial system may be considered as a "sparse polynomial system".
- Families of systems give rise to geometry.
- We exploit geometry for solving.

Sparse polynomial systems

A vector $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{Z}^n$ is the exponent vector of the (Laurent) monomial

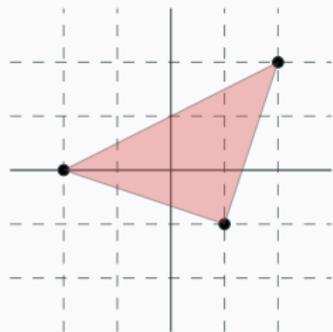
$$x^\alpha = x_1^{\alpha_1} \cdots x_n^{\alpha_n}.$$

A set $\mathcal{A} \subseteq \mathbb{Z}^n$ is the support of a polynomial f if the exponent vector of every term of f lies in \mathcal{A} .

Example: Let $\mathcal{A} \subseteq \mathbb{Z}^2$ be the point set \rightarrow

A polynomial of support \mathcal{A} has the form

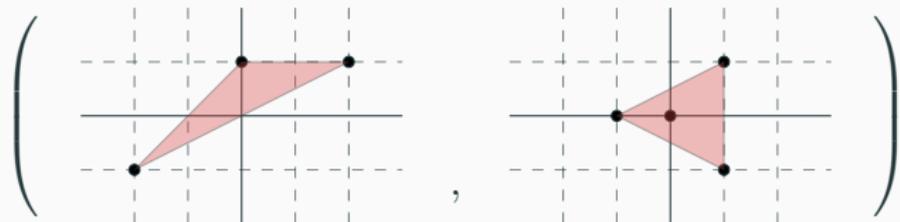
$$f = c_{(2,2)}x^2y^2 + c_{(1,-1)}xy^{-1} + c_{(-2,0)}x^{-2}.$$



Sparse polynomial systems

The set of [sparse polynomial systems](#) of support $\mathcal{A}_\bullet = (\mathcal{A}_1, \dots, \mathcal{A}_n)$ (with $\mathcal{A}_i \subseteq \mathbb{Z}^n$) consists of systems $F = (f_1, \dots, f_n)$ where f_i has support \mathcal{A}_i .

Example: Let $\mathcal{A}_\bullet = (\mathcal{A}_1, \mathcal{A}_2)$ be the set of supports below.



A sparse polynomial system of support \mathcal{A}_\bullet has the form

$$F = \begin{pmatrix} c_{(2,1)}x^2y + c_{(0,1)}y + c_{(-2,-1)}x^{-2}y^{-1} \\ c_{(1,1)}xy + c_{(1,-1)}xy^{-1} + c_{(-1,0)}x^{-1} + c_{(0,0)} \end{pmatrix}.$$

Sparse polynomial systems

Write $\mathbb{C}^{\mathcal{A}_\bullet}$ for the space of sparse polynomial systems of support \mathcal{A}_\bullet .

- We care about solutions in the algebraic torus $(\mathbb{C}^\times)^n$.
- The zero set of $F \in \mathbb{C}^{\mathcal{A}_\bullet}$ is $\mathcal{V}(F) = \{x \in (\mathbb{C}^\times)^n : F(x) = 0\}$.

Goal: We want to compute numerical solutions to sparse polynomial systems (using some geometric structure).

Question: What is the number of solutions to a general system of support \mathcal{A}_\bullet ?

Sparse polynomial systems

- For a subset $S \subseteq \mathbb{R}^n$, let $\text{conv}(S)$ denote the convex hull.
- The mixed volume of convex bodies $C_1, \dots, C_n \subseteq \mathbb{R}^n$ is the coefficient of $t_1 \cdots t_n$ in

$$\text{Vol}(t_1 C_1 + \cdots + t_n C_n).$$

- Write $MV(\mathcal{A}_\bullet)$ for the mixed volume of the convex bodies $\text{conv}(\mathcal{A}_1), \dots, \text{conv}(\mathcal{A}_n)$.

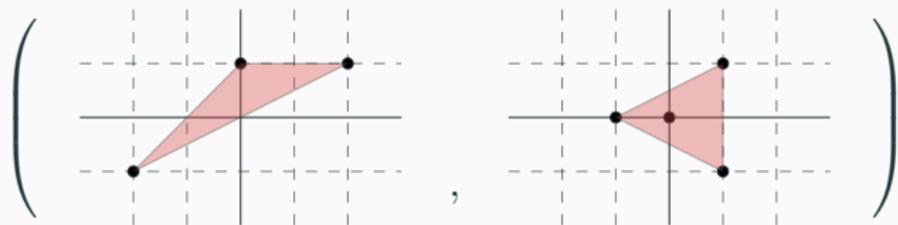
Theorem (Bernstein)

There are at most $MV(\mathcal{A}_\bullet)$ many isolated zeros of a system $F \in \mathbb{C}^{\mathcal{A}_\bullet}$.

There is a Zariski open set of $\mathbb{C}^{\mathcal{A}_\bullet}$ where this bound is attained.

Sparse polynomial systems

Example: Recall the supports \mathcal{A}_\bullet from before.



A sparse polynomial system of support \mathcal{A}_\bullet has the form

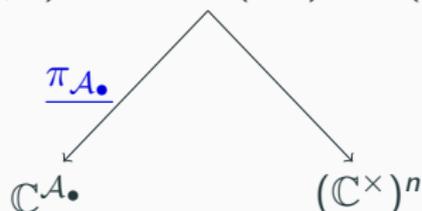
$$F = \begin{pmatrix} c_{(2,1)}x^2y + c_{(0,1)}y + c_{(-2,-1)}x^{-2}y^{-1} \\ c_{(1,1)}xy + c_{(1,-1)}xy^{-1} + c_{(-1,0)}x^{-1} + c_{(0,0)} \end{pmatrix}.$$

Macaulay2 helps to show that $MV(\mathcal{A}_\bullet) = 10$.

Sparse polynomial systems

There is an incidence correspondence:

$$\Gamma = \{(F, x) \in \mathbb{C}^{\mathcal{A}_\bullet} \times (\mathbb{C}^\times)^n : F(x) = 0\}$$



- Γ is a smooth, irreducible variety of dimension $\mathbb{C}^{\mathcal{A}_\bullet}$.
- The fiber $\pi_{\mathcal{A}_\bullet}^{-1}(F)$ is the zero set $\mathcal{V}(F)$.
- Over a Zariski open set, $\pi_{\mathcal{A}_\bullet}$ restricts to a smooth $\text{MV}(\mathcal{A}_\bullet)$ -to-1 covering space.

Such a map is a [branched cover](#).

Decomposable branched covers

A branched cover $\pi : \Gamma \rightarrow P$ is decomposable if it factors through nontrivial branched covers over a Zariski open set,

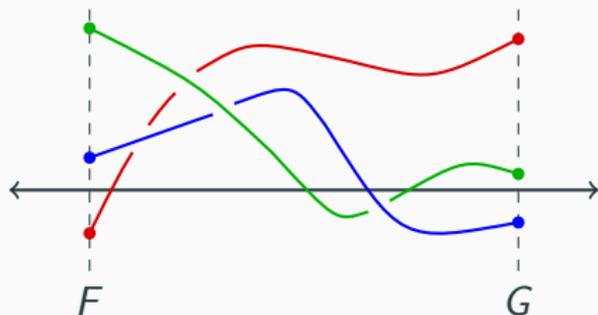
$$\pi : \Gamma \xrightarrow{\mu} \Lambda \xrightarrow{\phi} P.$$

- Fibers can be computed "in stages".
- Can be exploited by homotopy methods.

How do we exploit this structure?

Obligatory homotopy continuation slide

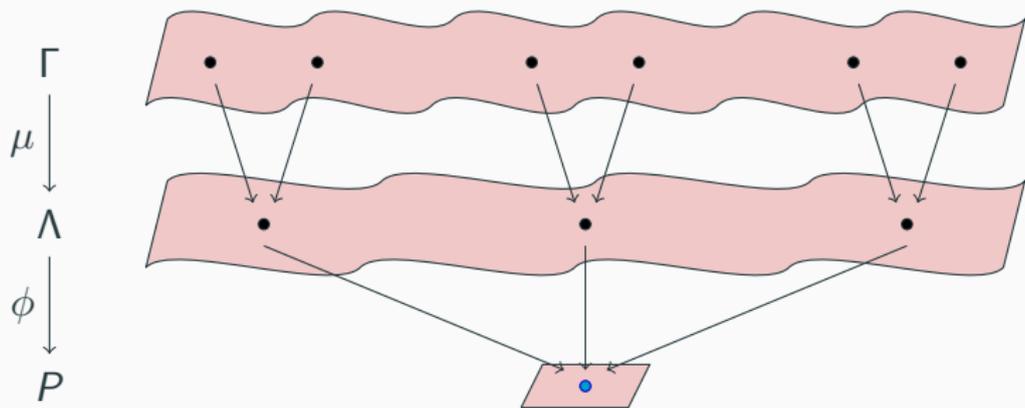
Uses numerical methods to “track” solutions from a “start system” F to a “target system” G .



- Allows us to numerically compute fibers, given a general fiber.

Decomposable branched covers

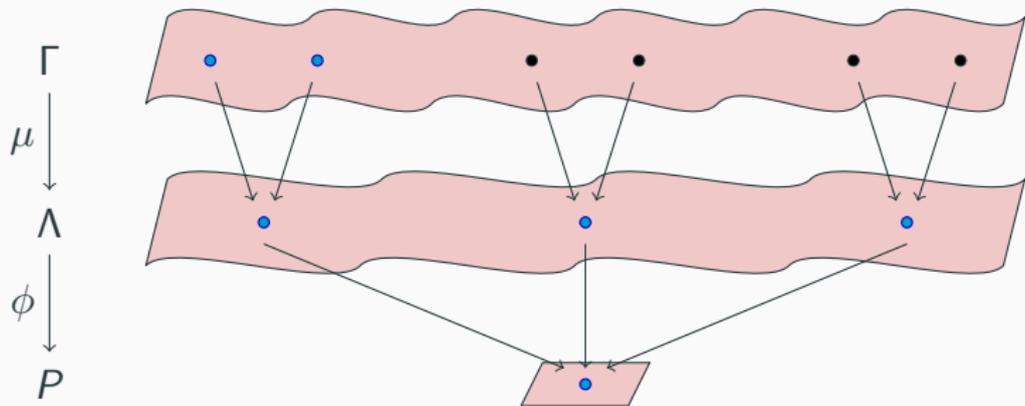
We exploit decomposability by computing only a partial fiber.



We use homotopy methods!

Decomposable branched covers

We exploit decomposability by computing only a partial fiber.

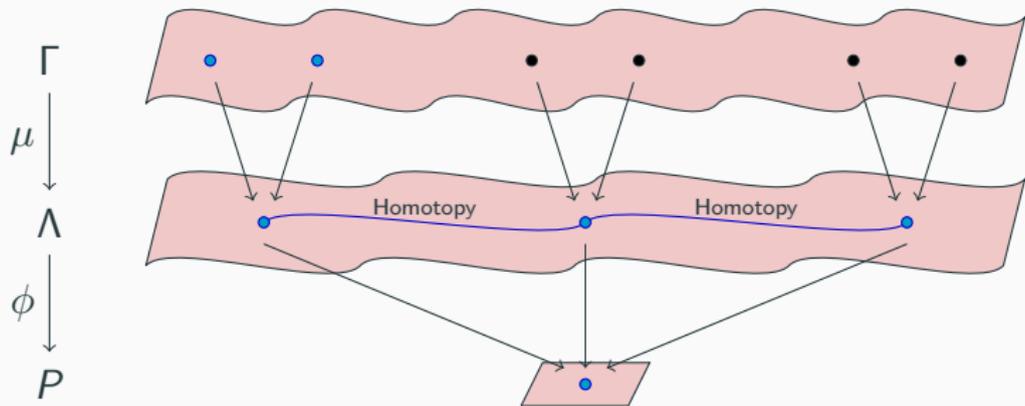


Other points of the fiber are recovered using homotopy continuation!

Now how to detect decomposability?

Decomposable branched covers

We exploit decomposability by computing only a partial fiber.



Other points of the fiber are recovered using homotopy continuation!

Now how to detect decomposability?

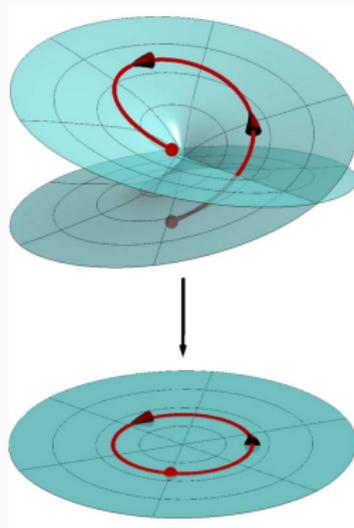
Decomposable branched covers

Let $\pi : \Gamma \rightarrow P$ be a branched cover.

- π has a well-defined monodromy group, defined by lifting based loops.
- The monodromy group is defined up to isomorphism.

Definition

The [Galois group](#) \mathcal{G}_π of a branched cover $\pi : \Gamma \rightarrow P$ is its monodromy group.

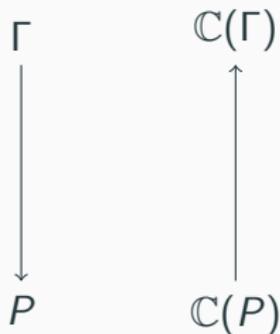


Decomposable branched covers

Question: Why are these called Galois groups?

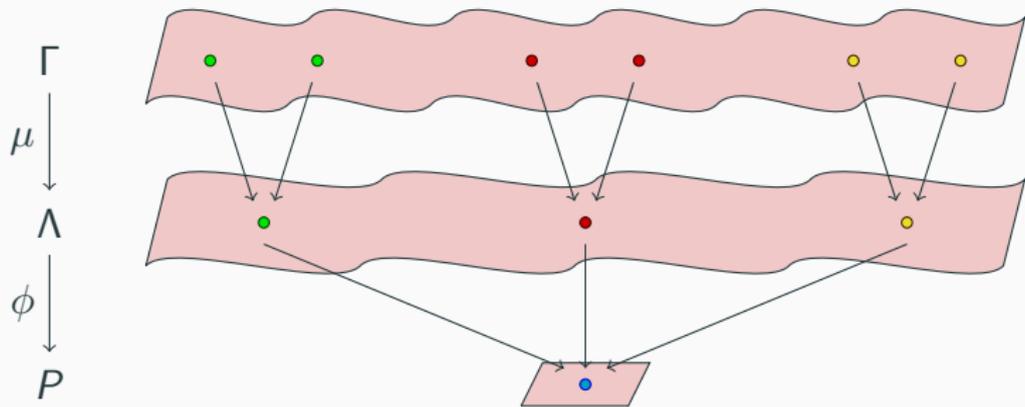
Answer: Jordan first defined them algebraically!

- A branched cover $\pi : \Gamma \rightarrow P$ induces a reverse inclusion of function fields.
- \mathcal{G}_π is isomorphic to the Galois group $\text{Gal}_{\mathbb{C}(P)}(\overline{\mathbb{C}(\Gamma)})$.



Decomposable branched covers

Galois groups of decomposable branched covers are imprimitive.



If the monodromy group is based at $F \in P$, invariant blocks are given by fibers $\mu^{-1}(G)$ for $G \in \phi^{-1}(F)$.

Decomposable branched covers

Theorem (Pirola, Schlesinger)

A branched cover $\pi : \Gamma \rightarrow P$ is decomposable if and only if its Galois group \mathcal{G}_π is imprimitive.

- We use this to detect decomposability!

How does this fit into the scope of sparse polynomial systems?

Galois groups of sparse polynomial systems

Let $\mathcal{G}_{\mathcal{A}_\bullet}$ be the Galois group of the branched cover $\pi_{\mathcal{A}_\bullet} : \Gamma \rightarrow \mathbb{C}^{\mathcal{A}_\bullet}$ corresponding to the set of supports \mathcal{A}_\bullet .

Esterov found 2 conditions for which \mathcal{A}_\bullet is decomposable. Such \mathcal{A}_\bullet and systems of support \mathcal{A}_\bullet are called..

- Lacunary: similar to $f(x^3) = 0$.
- Triangular: similar to $f(x, y) = g(y) = 0$.

Galois groups of sparse polynomial systems

Given a subset $I \subseteq \{1, \dots, n\}$, let

$$\mathbb{Z}\mathcal{A}_I = \{\alpha - \beta : \alpha, \beta \in \mathcal{A}_i \text{ for } i \in I\} \subseteq \mathbb{Z}^n$$

be the affine span of the set of supports.

Definition

The support \mathcal{A}_\bullet is lacunary if $\mathbb{Z}\mathcal{A}_\bullet$ is a proper subgroup of full rank.

Example: Consider the sparse polynomials of support $\mathcal{A} = \{0, 2, 4\}$.

Those polynomials have the form $f = c_0 + c_2x^2 + c_4x^4$.

Galois groups of sparse polynomial systems

If \mathcal{A}_\bullet is lacunary, there is a (monomial) change of coordinates such that every $F \in \mathbb{C}^{\mathcal{A}_\bullet}$ has the form

$$F(x_1, \dots, x_n) = G(x_1^{\alpha_1}, \dots, x_n^{\alpha_n}).$$

The system G is called the reduced system of F .

To solve lacunary systems, one..

(0. Applies a monomial change of coordinates.)

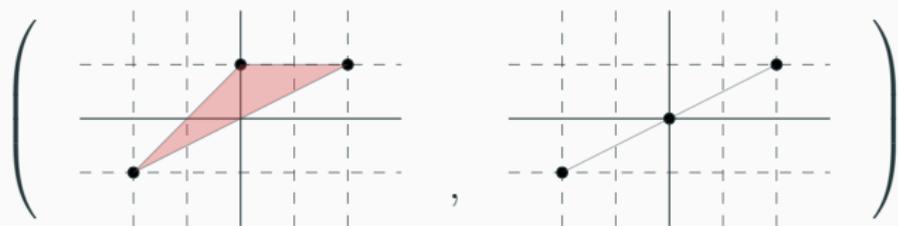
1. Solve the reduced system G .
2. Extracts roots to obtain zeros of F .

Galois groups of sparse polynomial systems

Definition

The support \mathcal{A}_\bullet is triangular if there is a nonempty proper subset $I \subseteq \{1, \dots, n\}$ such that $\text{rank } \mathbb{Z}\mathcal{A}_I = |I|$.

Example: Consider the supports $\mathcal{A}_\bullet = (\mathcal{A}_1, \mathcal{A}_2)$ below.



The subset $I = \{2\}$ shows this support is triangular. The second polynomial has the form

$$f_2 = c_{(2,1)}x^2y + c_{(0,0)} + c_{(-2,-1)}x^{-2}y^{-1}.$$

Galois groups of sparse polynomial systems

If \mathcal{A}_\bullet is triangular, there is a (monomial) change of coordinates such that every $F \in \mathbb{C}^{\mathcal{A}_\bullet}$ has the form

$$F(x_1, \dots, x_n) = (G(x_1, \dots, x_k), H(x_1, \dots, x_n)).$$

The system G is called a subsystem of F .

To solve triangular systems, one..

(0. Applies a monomial change of coordinates.)

1. Solve the subsystem G .
2. Substitute a zero of G into H and solve the residual system.
3. Apply homotopy techniques to compute remaining solutions.

Galois groups of sparse polynomial systems

Theorem (Esterov)

If \mathcal{A}_\bullet is lacunary or triangular, the Galois group $\mathcal{G}_{\mathcal{A}_\bullet}$ is imprimitive. Otherwise, $\mathcal{G}_{\mathcal{A}_\bullet}$ is the symmetric group.

- As a result, we understand which sparse polynomial systems are decomposable!
- The theorem above does not determine the Galois group when \mathcal{A}_\bullet is lacunary or triangular. This is an open problem!

Solving sparse polynomial systems

We can take this one step further! Let $F \in \mathbb{C}^{\mathcal{A}_\bullet}$.

- If \mathcal{A}_\bullet is lacunary, the reduced system G may be decomposable!
- If \mathcal{A}_\bullet is triangular, the subsystem G and the residual system may be decomposable!

This leads to a recursive algorithm for solving sparse polynomial systems.

Solving sparse polynomial systems

`solveDecomposableSystem`

Input:

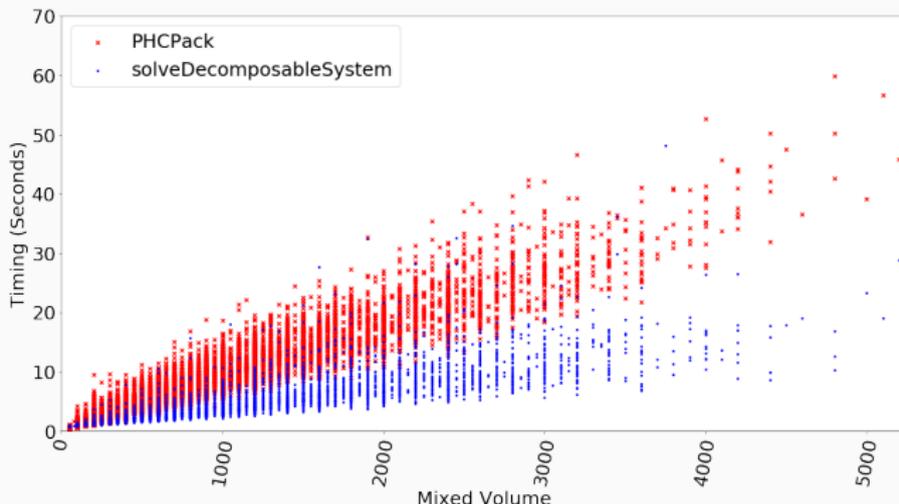
- General sparse system: $F \in \mathbb{C}^A$.
 - A blackbox solver: `solver`
-

1. If \mathcal{A}_\bullet is lacunary
 - a. Use `solveDecomposableSystem` on the reduced system
 - b. Extract roots
2. If \mathcal{A}_\bullet is triangular
 - a. Use `solveDecomposableSystem` on the subsystem
 - b. Use `solveDecomposableSystem` on the residual system
 - c. Use homotopy methods to recover all zeros
3. Else, use `solver` on F .

Solving sparse polynomial systems

Result: It works! And well!

We implemented and tested the method above against our choice of blackbox solver PHCPack. The generated systems of 5 polynomials were lacunary with 2 subsystems and varying numbers of solutions.



Solving sparse polynomial systems

We use decomposability for reducing computation in solving sparse polynomial systems. There is room for improvement!

- Decomposability corresponds to imprimitivity in the Galois group. How else can we use the Galois group?
- The Galois group isn't known in the case that \mathcal{A}_\bullet is lacunary or triangular! There may be more to this story.
- How to use decomposability for other classes of systems?

Thank you all for your time!

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[1, 2, 3, 4, 5, 6]

Solving sparse polynomial systems

If $\pi : \Gamma \xrightarrow{\mu} \Lambda \xrightarrow{\phi} P$ is a branched cover and $\mathcal{G}_\phi \subseteq S_d$, \mathcal{G}_π is contained in the wreath product

$$\mathcal{G}_\mu \wr \mathcal{G}_\phi = (\mathcal{G}_\mu)^d \rtimes \mathcal{G}_\phi.$$

\mathcal{G}_π may be a proper subgroup of this wreath product.

Example: Let $\mathcal{A}_\bullet = (\mathcal{A}_1, \mathcal{A}_2)$ be the set of supports below.



The expected wreath product is $\mathbb{Z}/2\mathbb{Z} \wr S_4$, but the Galois group is $\mathcal{G}_{\mathcal{A}_\bullet} = (\mathbb{Z}/2\mathbb{Z} \wr S_4) \cap A_8$.

Solving sparse polynomial systems

We say \mathcal{A}_\bullet is simple if $\pi_{\mathcal{A}_\bullet}$ factors into nontrivial branched covers $\pi_{\mathcal{A}_\bullet} = \mu \circ \phi$ where neither μ nor ϕ is decomposable.

Conjecture

Assume \mathcal{A}_\bullet is simple.

- If \mathcal{A}_\bullet is lacunary, $\mathcal{G}_{\mathcal{A}_\bullet} \subseteq T \wr S_d = T^d \rtimes S_d$ where $T \simeq \mathbb{Z}^n / \mathbb{Z}\mathcal{A}_\bullet$ is a finite abelian group. There is a map $\theta : T \wr S_d \rightarrow T$ and $\mathcal{G}_{\mathcal{A}_\bullet} \simeq \theta^{-1}(H)$ for some subgroup $H \subseteq T$.
- If \mathcal{A}_\bullet is triangular, $\mathcal{G}_{\mathcal{A}_\bullet} \subseteq S_k \wr S_d$ and either $\mathcal{G}_{\mathcal{A}_\bullet} = S_k \wr S_d$ or $\mathcal{G}_{\mathcal{A}_\bullet} = S_k \times S_d$.